
Symmetry Handling in MIP solvers

Domenico Salvagnin
DEI, University of Padova

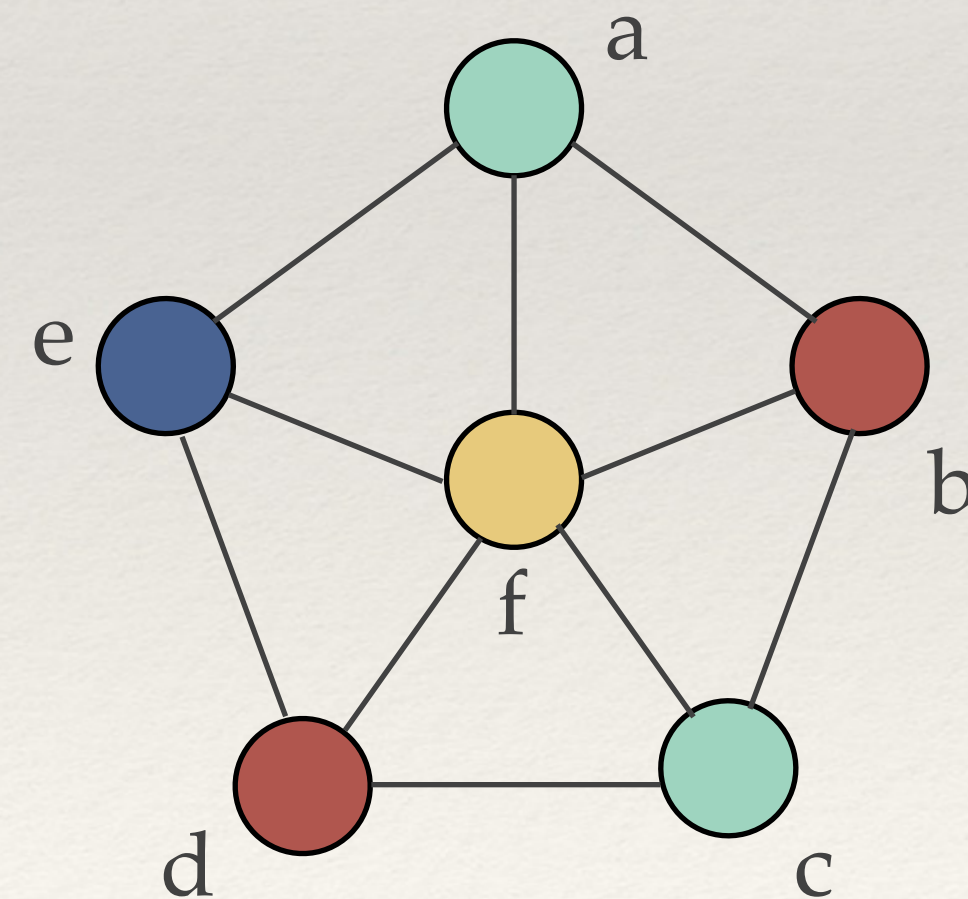
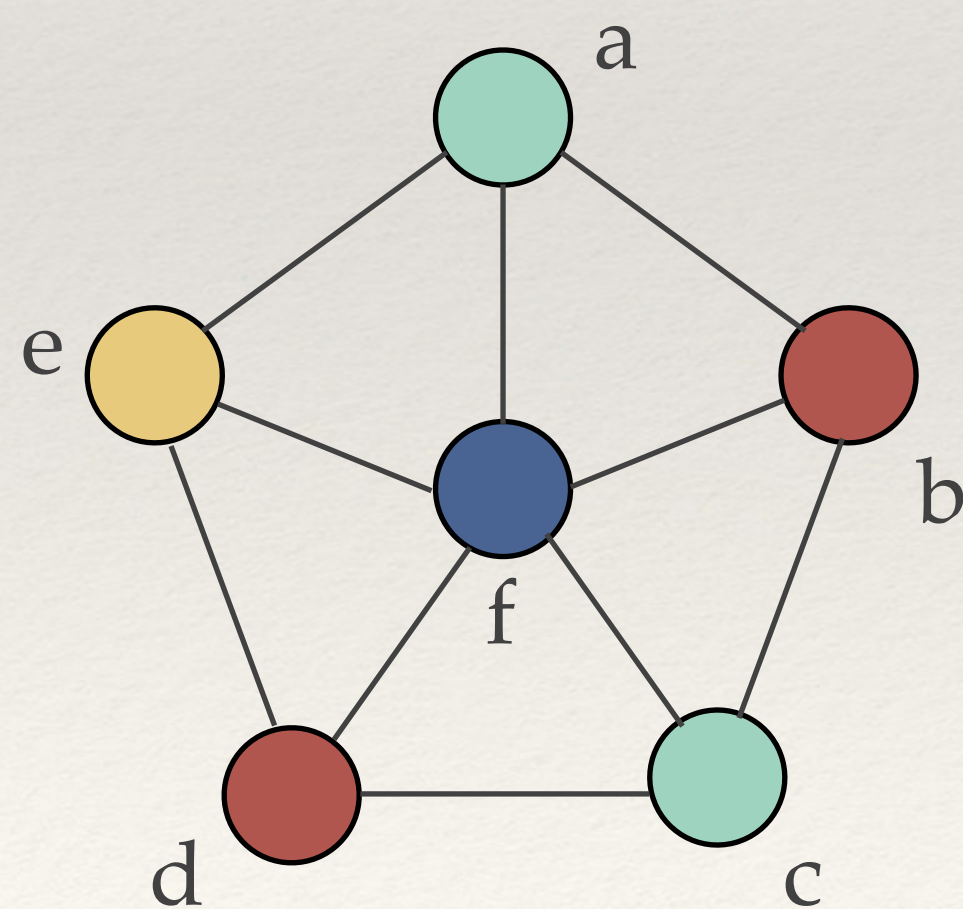
Agenda

- ❖ What is a Symmetry?
- ❖ Symmetry Detection
- ❖ Symmetry Representation (Group Theory)
- ❖ Discrete Optimization
 - ❖ Orbital branching / fixing / probing
- ❖ Continuous Optimization
 - ❖ Fractional Symmetries
 - ❖ LP folding / folding eliminations

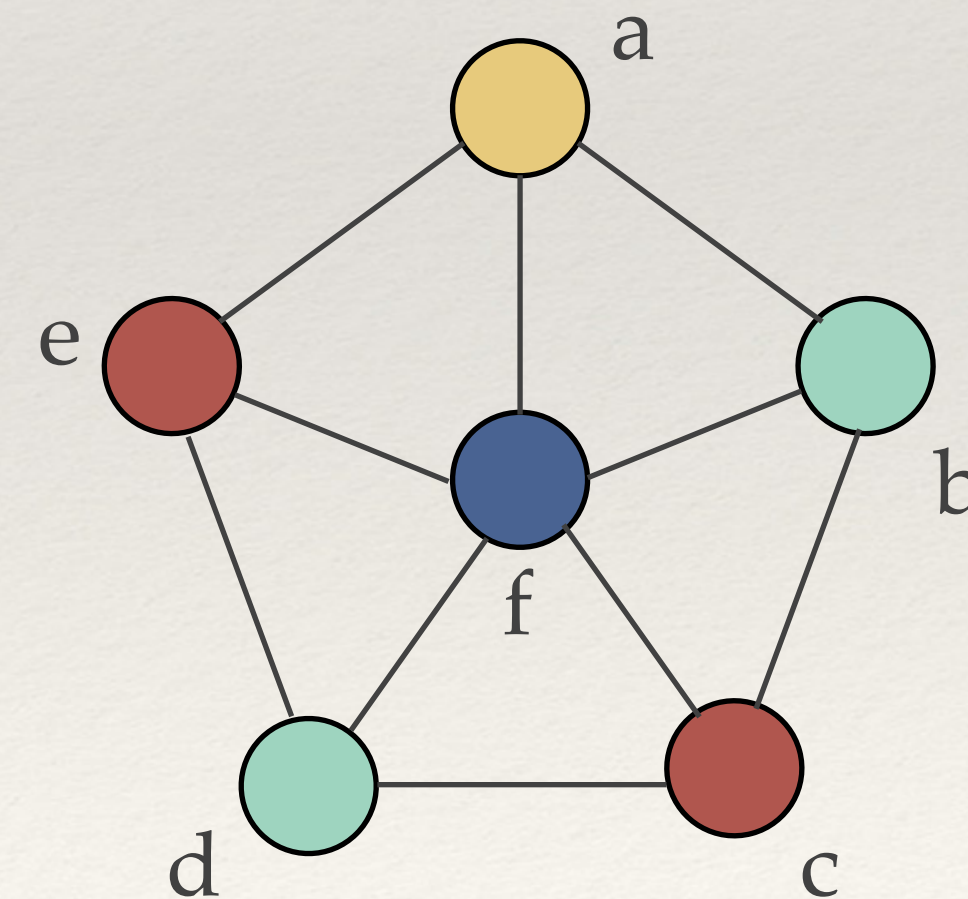
Introduction

(Permutation) Symmetries in Optimization

- ❖ What is a symmetry in an optimization problem?
- ❖ Intuitively, a symmetry is a permutation π that we can apply to feasible solutions and that always returns (other) feasible solutions (of the same cost).



swap two colors



rotate graph

(Permutation) Symmetries in Optimization

- ❖ Is this good or bad news?
- ❖ In some sense, symmetries point to some redundant information in the problem:
 - ❖ If **not** exploited, this usually means useless work by the algorithm :-)
 - ❖ If exploited, they can lead to improved performance :-)
- ❖ How to exploit them depends on the class of problems and algorithms
- ❖ But first...how do we detect symmetries in a problem?

Symmetry Detection

Formulation Symmetries

- ❖ Given an optimization problem P with feasible set $F(P)$ and objective function f , the definition of a permutation symmetry π given so far is along the following lines:

$$x \in F(P) \Leftrightarrow \pi(x) \in F(P) \quad f(x) = f(\pi(x))$$

- ❖ Utterly useless: we don't know the set of feasible solutions of a problem :-)
- ❖ In practice we resort to *formulation symmetries*, i.e., symmetries that keep the formulation of the problem invariant.
- ❖ Note that this is a **weaker** definition, easily fooled by innocuous changes to a formulation, like scaling or adding a redundant constraint!

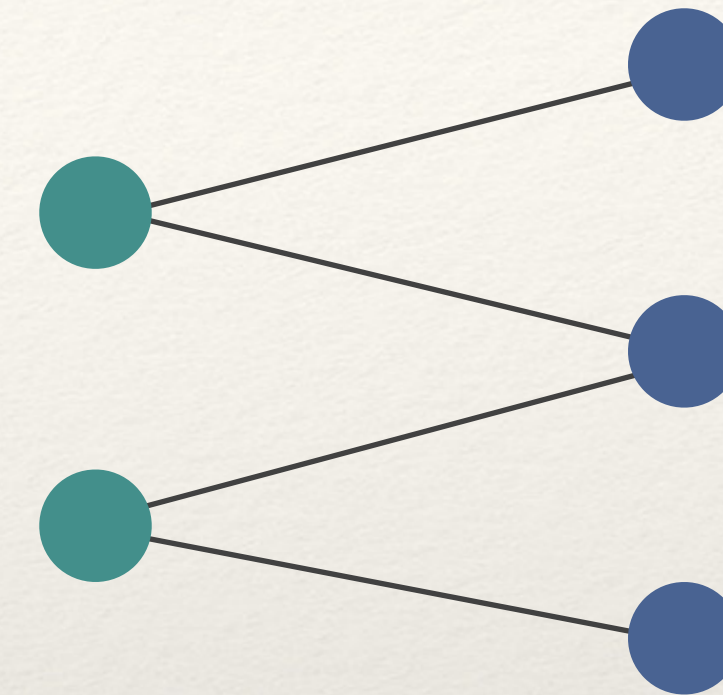
Formulation Symmetries

- ❖ A variable symmetry π is valid if there exists a corresponding constraint symmetry σ that keeps the *formulation* of the problem the same
- ❖ Concept is the same for more general constraints (arbitrary mathematical programs in algebraic form)
- ❖ Formulation is encoded as a *vertex-coloured graph*
 - ❖ Again, very generic, not restricted to MILP
 - ❖ We can apply standard methods / packages to compute graph automorphisms
 - ❖ *Complexity unknown but usually fast in practice*

Symmetry Graph

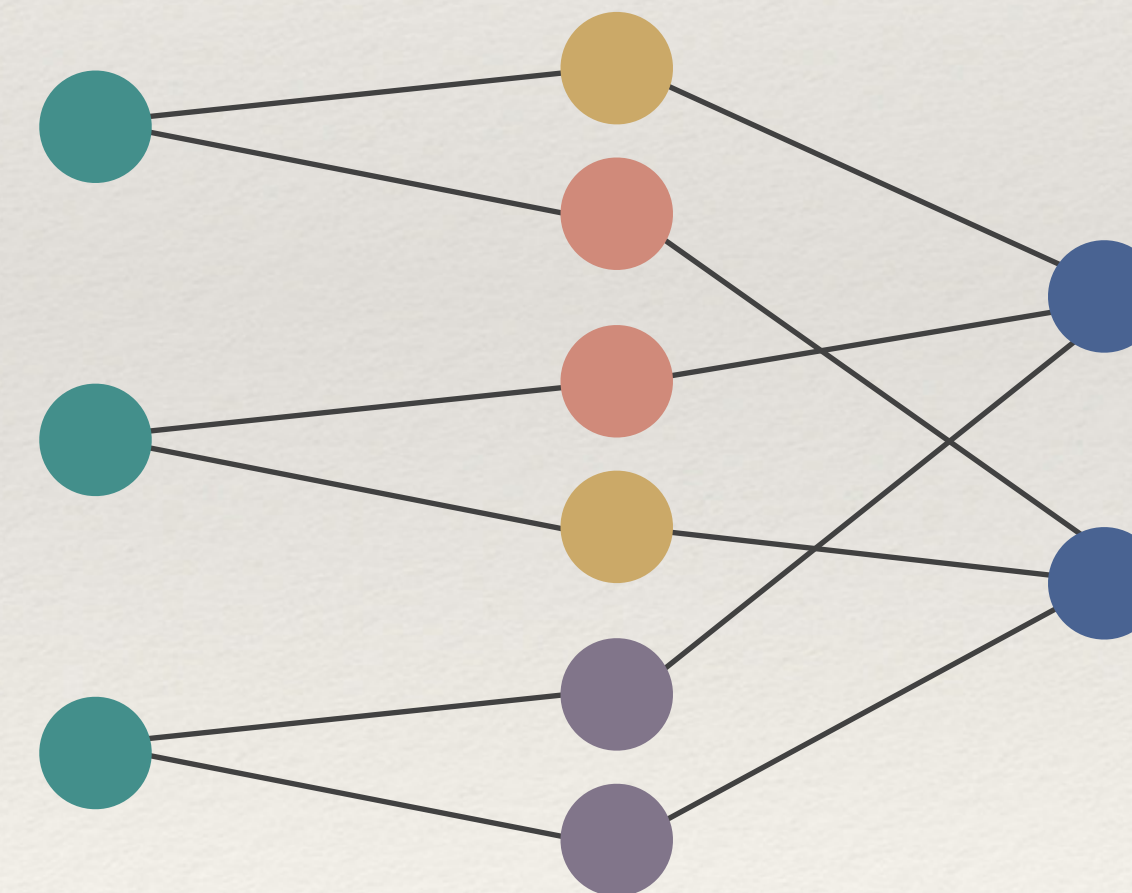
binary

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$



general

$$\begin{bmatrix} 1 & 2 \\ 2 & 1 \\ 3 & 3 \end{bmatrix}$$



Can be simplified: connect directly row-col pairs corresponding to most frequent coefficient!

Symmetry Representation

Symmetric Group

- ❖ How are the symmetries of a problem represented?
- ❖ A naïve way is to store the list of all symmetries...but this would work only on toy problems:
 - ❖ *Consider a graph coloring problem with 20 colors: that alone would give $20! > 10^{18}$ symmetries!*
- ❖ The key observation is to note that the symmetries of a problem form a (finite) **group**:
 - ❖ Any finite group can be represented by a (polynomially sized) list of **generators** (like in a vector space).

Group Concepts

- ❖ The group theory point of view is key in computing with (and exploiting) symmetries.
- ❖ Given a group G acting on ground set N (*in our case, the formulation symmetries acting on the variables of the problem*), we can define the two fundamental concepts:

Orbit of an object x

$$G(x) = \{g(x), g \in G\}$$

*Set of objects that x can
be mapped to by
permutations in G*

Stabilizer of a set S

$$\text{stab}(G, S) = \{g \in G \mid g(S) = S\}$$

*Set of permutations that
map the objects in S to
themselves
(a subgroup of G)*

Group Concepts

- ❖ Why are those two concepts important?
 - ❖ Orbits tell us which objects (variables) are interchangeable given a symmetry group
 - ❖ Stabilizers tell us which symmetries are still valid after we have taken some branching decisions
 - ❖ Note that we can (and do) compute orbits w.r.t. a stabilizer...
- ❖ Orbits partition the set of variables into equivalence classes, so we often talk of *orbit partition*.

Group Computations

- ❖ Orbits can be computed in linear time given generators
 - ❖ Standard union-find data structure
- ❖ For stabilizers it depends...
 - ❖ For point-wise stabilizers (each element of S is mapped to itself), it can be done in polynomial time (but the polynomial is not great...).
 - ❖ For set-wise stabilizers (the set S is mapped to itself as a whole), the complexity is the same as for graph automorphism :-)
 - ❖ In general the latter concept is more powerful but more expensive to compute (exactly).

Discrete Optimization

Orbital Branching

- ❖ Consider an orbit $O = \{x_{i1}, \dots, x_{ik}\}$ of binary variables at the root of the branch-and-bound tree.
- ❖ Standard branching would pick one (say the first), and apply the disjunction:

$$x_{i_1} = 1 \vee x_{i_1} = 0$$

- ❖ However, the right branch still contains all the symmetric solutions $x_{i2}=1, x_{i3}=1, \dots$
- ❖ This is even more explicit by considering (still valid) $k+1$ branch:

$$x_{i_1} = 1 \vee \dots \vee x_{i_k} = 1 \vee x_{i_1} = \dots = x_{i_k} = 0$$

Orbital Branching

- ❖ The gist of orbital branching is to drop all the equivalent branches (except one) and thus consider the disjunction:

$$x_{i_1} = 1 \vee x_{i_1} = \dots = x_{i_k} = 0$$

- ❖ The same can be done when branching on a general integer variable: the standard disjunction:

$$x_{i_1} \geq v + 1 \vee x_{i_1} \leq v$$

becomes

$$x_{i_1} \geq v + 1 \vee x_{i_1} \leq v, \dots, x_{i_k} \leq v$$

Orbital Branching

- ❖ What about the rest of the tree?
- ❖ The logic is exactly the same, but we need to use an appropriate stabilizer of the global symmetry group for computing the orbits!
- ❖ The most general approach consists in keeping track of which bound changes are *symmetry breaking* (branching only so far) and which are not, and compute the stabilizer w.r.t. those only
- ❖ The stabilizer will thus only map variables with tightened bounds (by branching) only to other variables with the same bounds.
 - ❖ *Simple case: variables fixed to one (resp. zero) by branching can only map to other variables fixed to one (resp. zero) by branching.*

Orbital Fixing

- ❖ This tries to apply the orbital logic to tightenings that come from other arguments (primal reductions, reduced cost fixing, etc...)
- ❖ Consider the orbits at the current node (again, those are computed w.r.t. a stabilizer that only considers symmetry breaking bound changes).
- ❖ Within each orbit, compute the maximum lower bound L and the minimum upper bound U , and set them for all variables in the orbit.
- ❖ *Example: if reduced cost fixing deduces that a variable in an orbit can be fixed zero, we would fix to zero all the variables in the same orbit.*
- ❖ This is why we need to distinguish symmetry bound changes: otherwise orbital fixing would never tighten anything...

Orbital Probing

- ❖ For each orbit of integer variables:
 - ❖ Fix all the variables in the orbit to their (identical) lower bound v
 - ❖ Perform constraint propagation
 - ❖ If infeasible we can set one variable in the orbit to $v+1$
 - ❖ **Update orbits**



also a symmetry breaking bound change!

Results

NO SYMMETRY						SYMMETRY					
class	#	#S	time	nodes	PDI	#S	tQ	nQ	pdiQ	W/L	
all	4190	3970	166.88	2327	42.46	4010***	0.93***	0.86***	0.96***	43/13	
[0,3600}	4028	3970	146.68	1896	39.24	4010***	0.92***	0.86***	0.96***	43/13	
[1,3600}	4016	3958	147.95	1925	39.47	3998***	0.92***	0.86***	0.96***	43/13	
[10,3600}	3874	3816	161.72	2199	41.85	3856***	0.92***	0.85***	0.96***	43/13	
[100,3600}	2293	2235	361.45	5773	71.21	2275***	0.87***	0.78***	0.94***	36/9	
[1000,3600}	452	394	1703.72	99885	172.40	434***	0.64***	0.50***	0.78***	13/3	
all-opt	3952	3952	138.30	1654	38.14	3952	0.95***	0.89***	0.98***	33/11	
[0,0)	0	0	0.00	0	0.00	0	1.00	1.00	1.00	0/0	
[0,1)	12	12	0.41	1	0.30	12	1.01	1.00	1.02	0/0	
[1,10)	142	142	6.16	42	3.72	142	1.00	0.99	1.01	0/0	
[10,100)	1581	1581	46.08	537	17.04	1581	1.00	0.97***	1.01	5/1	
[100,1000)	1841	1841	245.19	2863	56.58	1841	0.94***	0.87***	0.99***	12/4	
[1000,3600)	376	376	1550.33	53566	177.49	376	0.82***	0.69***	0.89***	5/1	

FICO XPRESS 9.7 - 838 instances 5 seeds 16 threads

Continuous Optimization

Continuous Optimization

- ❖ All the symmetry handling techniques presented are discrete in nature and are applied during branch-and-bound
- ❖ Does it mean that there is nothing to do if the problem is continuous???
- ❖ To the contrary!!!
- ❖ If the problem is continuous and **convex**, we can do so much more :-)

Symmetry and Convexity

- ❖ The key intuition is that if the problem is convex, we can always “average” symmetrical solutions and thus assume that all variables within an orbit have the same value
- ❖ Consider a permutation swapping, among other things, the first and the second variable:

$$\begin{array}{ccc} (0, 1, *, *, *) & & \\ \downarrow \text{symmetry} & \left. \vphantom{\begin{array}{c} (0, 1, *, *, *) \\ (1, 0, *, *, *) \end{array}} \right\} & \xrightarrow[\text{combination}]{\text{convex}} \\ (1, 0, *, *, *) & & (1/2, 1/2, *, *, *) \end{array}$$

- ❖ Repeating the argument for all variables in all orbits gets the claim.

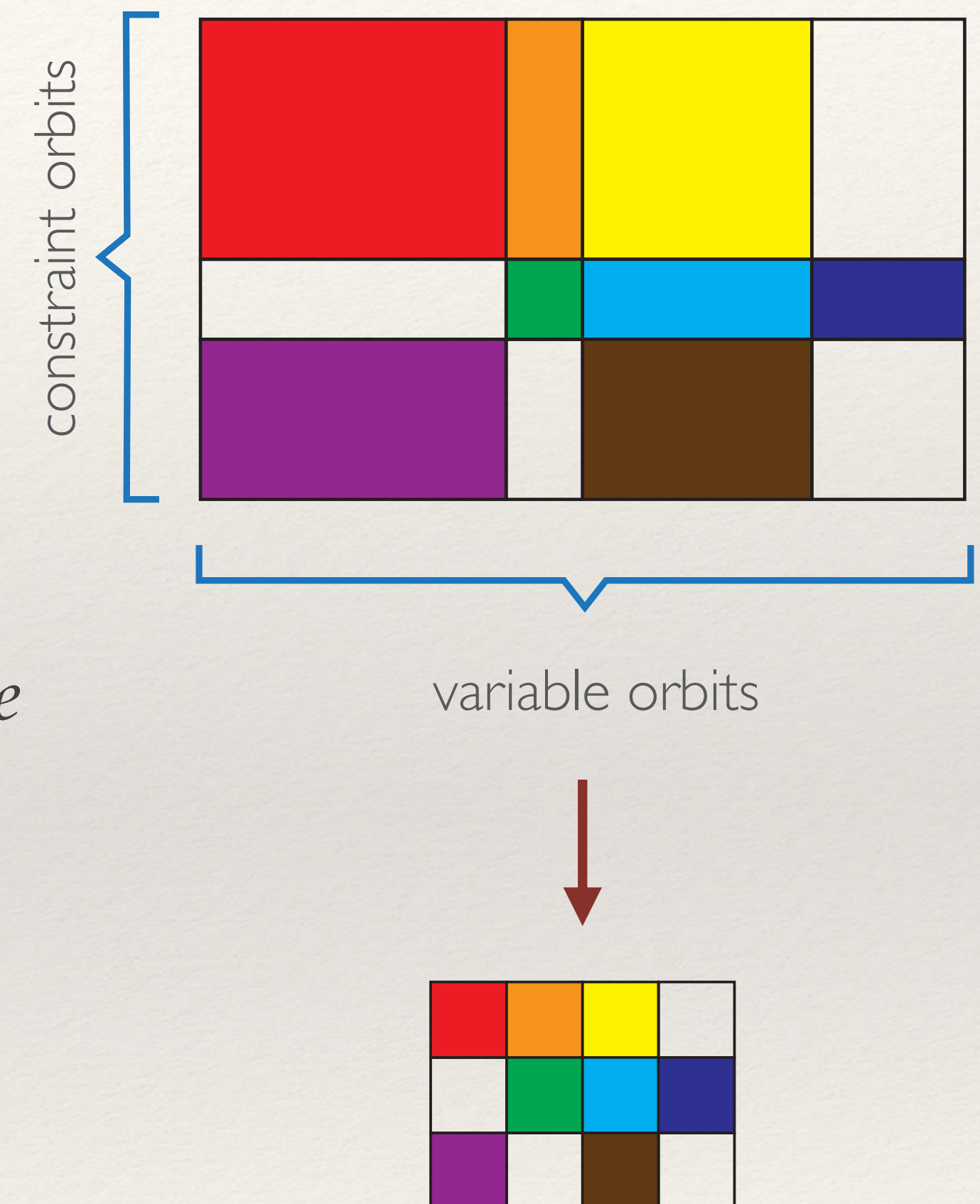
Orbital Shrinking

Not actually implemented, but simpler to understand:

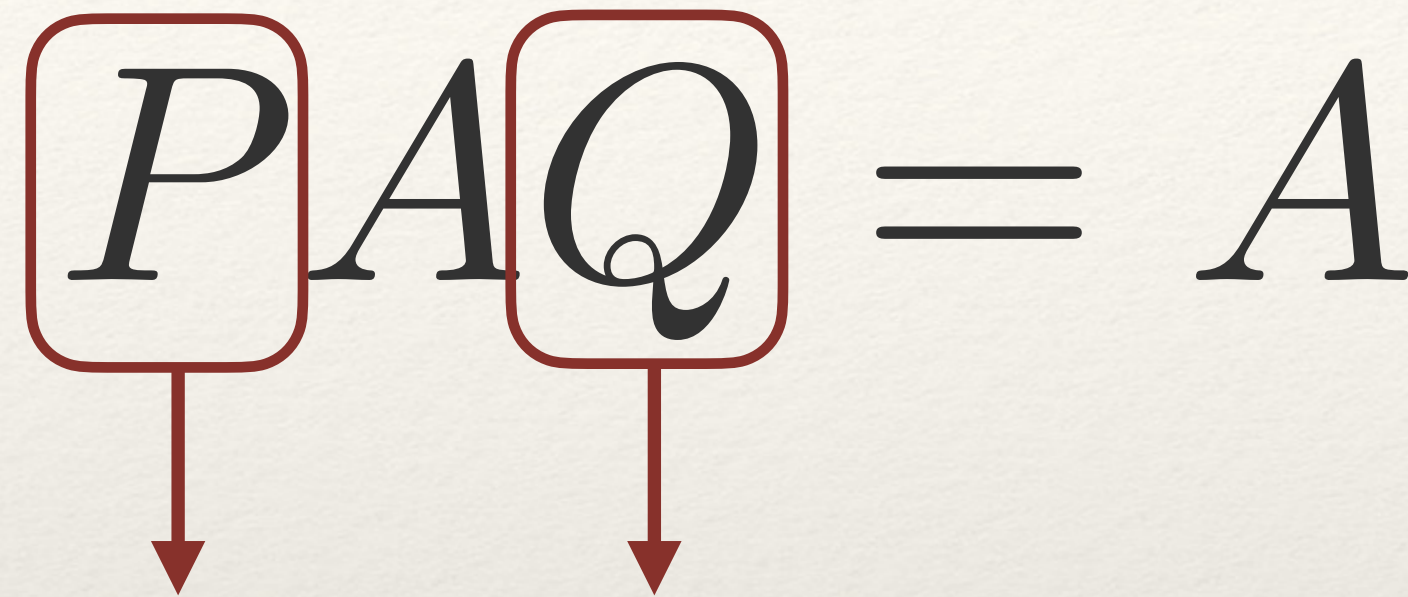
- ❖ Aggregate variables in the same column orbit
- ❖ *Convex continuous: can always average symmetric optimal solutions*
- ❖ Keep only one constraint for each row orbit
 - ❖ *All constraints in the same orbit would be identical copies after the variable aggregations above*

It is a no brainer if we already have the symmetry group available, but...

- ❖ Computing the symmetry group is potentially expensive
- ❖ We can actually do strictly better!!!



Fractional Symmetries

$$\boxed{P} A \boxed{Q} = A$$


~~*permutation matrices*~~

doubly-stochastic matrices

- ❖ Still valid in the convex continuous case
- ❖ Can be computed in polynomial time (and efficiently in practice)
- ❖ Give coarser (equitable) partitions than orbital partitions!

LP Folding

- ❖ Use equitable partition to shrink model
- ❖ Independent of symmetry detection for MIP
- ❖ Note that it does not give a basic solution for the original problem!
 - ❖ Nothing to do if interested in a primal-dual pair;
 - ❖ Need crossover otherwise (can be expensive)
- ❖ Enabled by default on when solving LPs
- ❖ Disabled by default when solving MIPs!

Results

NO LP FOLDING.						LP FOLDING					
class	#	#S	time	nodes	PDI	#S	tQ	nQ	pdiQ	W/L	
all	840	834	67.16	1	0.00	836	0.88***	1.00	1.00	30/4	
[0,3600}	836	834	65.76	1	0.00	836	0.88***	1.00	1.00	30/4	
[1,3600}	833	831	66.29	1	0.00	833	0.88***	1.00	1.00	30/4	
[10,3600}	667	665	105.86	1	0.00	667	0.87***	1.00	1.00	24/4	
[100,3600}	292	290	331.96	1	-0.00	292	0.78***	1.00	1.00	17/2	
[1000,3600}	40	38	2015.70	1	0.00	40	0.33***	1.00	1.00	2/0	
all-opt	834	834	65.06	1	0.00	834	0.89***	1.00	1.00	28/4	
[0,0)	0	0	0.00	0	0.00	0	1.00	1.00	1.00	0/0	
[0,1)	3	3	0.84	1	0.00	3	1.00	1.00	1.00	0/0	
[1,10)	166	166	4.23	1	0.00	166	0.88***	1.00	1.00	6/0	
[10,100)	375	375	39.88	1	0.00	375	0.95***	1.00	1.00	6/2	
[100,1000)	252	252	247.84	1	0.00	252	0.89***	1.00	1.00	10/2	
[1000,3600)	27	27	1523.75	1	0.00	27	0.49	1.00	1.00	1/0	

Folding Eliminations

- ❖ What if we have symmetries affecting continuous variables *only* in a MIP?
 - ❖ What does this even mean?
 - ❖ The symmetries must be valid for the *point-wise* stabiliser of the integer variables
 - ❖ Then we can still aggregate along those orbits (of continuous variables only)
- ❖ This is weaker than necessary:
 - ❖ We can again use fractional symmetries to compute a coarser partition (but still having each integer variable in a singleton block).

Results

-----+-----+-----												
		I	NO FOLDING ELIM				I	FOLDING ELIM				
class	#	I	#S	time	nodes	PDI	I	#S	tQ	nQ	pdiQ	W/L
-----+-----+-----												
all	4190	I	4002	156.16	2023	41.08	I	4010	0.99***	0.99	1.00**	10/3
[0,3600}	4013	I	4002	135.06	1609	37.58	I	4010	0.99***	0.99	1.00**	10/3
[1,3600}	3999	I	3988	136.41	1635	37.84	I	3996	0.99***	0.99	1.00**	10/3
[10,3600}	3837	I	3826	150.62	1858	40.46	I	3834	0.99***	0.99	1.00**	10/3
[100,3600}	2173	I	2162	347.51	4419	71.72	I	2170	0.98***	0.98	0.99*	9/2
[1000,3600}	363	I	352	1665.61	54241	178.73	I	360	0.92**	0.85**	1.00	3/0
-----+-----+-----												
all-opt	3999	I	3999	133.64	1585	37.56	I	3999	0.99*	1.00	1.00*	7/3
[0,0)	0	I	0	0.00	0	0.00	I	0	1.00	1.00	1.00	0/0
[0,1)	14	I	14	0.47	6	0.27	I	14	1.00	1.00	1.01	0/0
[1,10)	162	I	162	6.32	71	3.51	I	162	1.00	1.00	1.00	0/0
[10,100)	1664	I	1664	46.49	595	16.88	I	1664	1.00	1.00	1.00	1/1
[100,1000)	1810	I	1810	252.27	2670	59.09	I	1810	0.99*	1.01	0.99	4/0
[1000,3600)	349	I	349	1640.31	52495	188.79	I	349	0.98	0.97	0.99	1/0
-----+-----+-----												

Thanks for your attention!